



FP6-507728

EURON

European Robotics Research Network

Network of Excellence

Information Society Technologies Priority

DR 19.2

Proceedings from EUROS 2008

Due date of deliverable: 30 April 2008

Actual submission date: 2 June 2008

Start date of the project: 1 May 2004

Organisation name of lead contractor for this deliverable: KUL

Duration: 48 months

Revision: First version

Dissemination level: PU

The 2008 European Robotics Symposium (*EUROS'08*) was held on March 26th and 27th in Prague. (The public webpage of the event can be found [here](#).) The local organization was taken care of by Libor Přebil from the Department of Cybernetics, Czech Technical University in Prague. The papers presented at the conference are published as [Volume 44](#) in the *STAR* series (Springer Tracts on Advanced Robotics).

The event drew 98 participants, from all over the world, in a single-track format that provided a lot of opportunities for discussion and informal meetings. Of the 98 participants, 56 were senior EURON members, 24 were non-EURON members, and 24 were PhD students.

The conference had 21 oral paper presentations, and about the same number of oral poster presentations, on a wide range of robotics topics. Prof. Kevin Warwick, University of Reading, UK, gave a keynote lecture on *Robots with Biological Brains and Humans with Part Machine Brains*, which did not fail to stimulate the debate about the “boundaries” of robotics. The conference was closed with a well-attended tutorial on *Standardization in robotics: how can it help our research?*, by Martin Hägele and Erwin Prassler of the [Robot Standards](#) project *RoSta*, in which they explained the needs and benefits of (mainly software) standardization and harmonization in the robotics domain.

A scientific highlight of this EUROS was Prof. Khatib’s (Stanford University, USA) presentation: his group’s work on the control of humanoid robots has been going on for about 20 years and has now culminated in a total approach of the control problem, including the interaction control between humanoid robot and its environment; EUROS was the first conference worldwide on which this total approach has been presented.